

# A Broad Framework for Joint Modeling And Some Tales From the Unexpected

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# Common Ground for Various Settings

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<b>Sequential trials</b>	outcome & sample size
<b>Incomplete data</b>	outcome(s) & missingness process
<b>Completely random sample size</b>	outcome & sample size
<b>'Informative' cluster size</b>	outcome & cluster size
<b>Classical survival</b>	time to event & censorship
<b>(Narrow) joint modeling</b>	time to event(s) & longitudinal process
<b>Random observation times</b>	outcome & measurement schedule

# A Classic: Joint Models with Missing Data

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$$f(\mathbf{y}_i, \mathbf{r}_i | X_i, \boldsymbol{\theta}, \boldsymbol{\psi})$$

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**Selection Models:**  $f(\mathbf{y}_i | X_i, \boldsymbol{\theta})$   $f(\mathbf{r}_i | X_i, \mathbf{y}_i^o, \mathbf{y}_i^m, \boldsymbol{\psi})$

**MCAR**  $\longrightarrow$  **MAR**  $\longrightarrow$  **MNAR**

$$f(\mathbf{r}_i | X_i, \boldsymbol{\psi}) \quad f(\mathbf{r}_i | X_i, \mathbf{y}_i^o, \boldsymbol{\psi}) \quad f(\mathbf{r}_i | X_i, \mathbf{y}_i^o, \mathbf{y}_i^m, \boldsymbol{\psi})$$

**Pattern-mixture Models:**  $f(\mathbf{y}_i | X_i, \mathbf{r}_i, \boldsymbol{\theta}) f(\mathbf{r}_i | X_i, \boldsymbol{\psi})$

**Shared-parameter Models:**  $f(\mathbf{y}_i | X_i, \mathbf{b}_i, \boldsymbol{\theta}) f(\mathbf{r}_i | X_i, \mathbf{b}_i, \boldsymbol{\psi})$

# Generic Setting

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$$f(\mathbf{y}_i, \mathbf{c}_i | \boldsymbol{\theta}, \boldsymbol{\psi}) = f(\mathbf{y}_i | \boldsymbol{\theta}) \cdot f(\mathbf{c}_i | \mathbf{y}_i, \boldsymbol{\psi}) = f(\mathbf{y}_i | \mathbf{c}_i, \boldsymbol{\theta}, \boldsymbol{\psi}) \cdot f(\mathbf{c}_i | \boldsymbol{\theta}, \boldsymbol{\psi})$$

Setting	$Y_i$	$C_i$
<u>Sequential trials</u>	$Y_i$	$N$
<u>Incomplete data</u>	$Y_i$	$R_i$
<u>Completely random sample size</u>	$Y_i$	$N$
'Informative' cluster size	$Y_i$	$T_i$
Classical survival	$T_i$	$C_i$
(Narrow) joint modeling	$Y_i$	$T_i, \dots$
Random observation times	$Y_i$	$T_i$

# Fundamental Concepts

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## Ignorability:

$$f(\mathbf{c}_i | \mathbf{y}_i, \psi) = f(\mathbf{c}_i | \mathbf{y}_i^o, \psi)$$

combined with **separability**

## Ancillarity:

- ▷  $S$  minimally sufficient statistic for  $\theta$
- ▷  $T|S$  does not contain information about  $\theta$

## Completeness:

▷  $g(\cdot)$  a measurable function of  $S$

▷  $E[g(s)] = 0$  for all  $\theta \implies g(s) = 0$  a.e.

## Weights:

$$\begin{aligned} f(\mathbf{y}_i | \boldsymbol{\theta}^*, \boldsymbol{\psi}^*) &= f(\mathbf{y}_i | \mathbf{c}_i, \boldsymbol{\theta}^*) \cdot \frac{f(\mathbf{c}_i | \boldsymbol{\psi}^*)}{f(\mathbf{c}_i | \mathbf{y}_i, \boldsymbol{\theta}^*, \boldsymbol{\psi}^*)} \\ &= f(\mathbf{y}_i | \mathbf{c}_i, \boldsymbol{\theta}^*) \cdot w_i(\mathbf{y}_i, \mathbf{c}_i, \boldsymbol{\theta}^*, \boldsymbol{\psi}^*) \end{aligned}$$

$$\text{MAR: } w_i(\mathbf{y}_i, \mathbf{c}_i) = w_i(\mathbf{y}_i^o, \mathbf{c}_i)$$

## Deterministic rule:

$$w_i(\mathbf{y}_i^o, \mathbf{c}_i) \in \{0, 1\}$$

# Simple Setting

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- Observe

$$Y_i \sim N(\mu, 1) \quad i = 1, \dots, n$$

- Construct sum statistics

$$K = \sum_{i=1}^n Y_i$$

- Apply a stopping rule, e.g.,

$$F\left(\alpha + \frac{\beta}{n}k\right)$$

- If continuation applies, observe  $Y_i$ ,  $i = n + 1, \dots, 2n$

- Data:

$$(Y_1, \dots, Y_N, N)$$

# Stopping Rule

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$$F\left(\alpha + \frac{\beta}{n}k\right) = \Phi\left(\alpha + \frac{\beta}{n}k\right)$$

- Three important cases:

<b>Purely random sample size</b>	$\beta = 0$
<b>Probabilistic stopping</b>	$\beta \neq 0$
<b>Purely random sample size</b>	$\beta \rightarrow +\infty$



# Four Relevant Distributions

$Y$	$\prod_{i=1}^N \phi(y_i; \mu)$
$N Y$	$\Phi\left(\alpha + \frac{\beta}{n}k\right)$
$Y N$	$\frac{\prod_{i=1}^N \phi(y_i; \mu) \Phi\left(\alpha + \frac{\beta}{n}k\right)^z \left[1 - \Phi\left(\alpha + \frac{\beta}{n}k\right)\right]^{1-z}}{\Phi\left(\frac{\alpha + \beta\mu}{\sqrt{1 + \beta^2/n}}\right)^z \left[1 - \Phi\left(\frac{\alpha + \beta\mu}{\sqrt{1 + \beta^2/n}}\right)\right]^{1-z}}$
$N$	$\Phi\left(\frac{\alpha + \beta\mu}{\sqrt{1 + \beta^2/n}}\right)$

# Joint Likelihood

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$$L(\mu) = \prod_{i=1}^N \phi(y_i; \mu) \cdot \Phi\left(\alpha + \frac{\beta}{n}k\right)^z \cdot \left\{1 - \Phi\left(\alpha + \frac{\beta}{n}k\right)\right\}^{1-z}$$

$$\ell(\mu) = -\frac{1}{2} \sum_{i=1}^N (y_i - \mu)^2$$

$$S(\mu) = \sum_{i=1}^N (y_i - \mu)$$

$$H(\mu) = -N$$

# Conditional Likelihood

$$L_c(\mu) = \frac{\prod_{i=1}^N \phi(y_i; \mu) \Phi\left(\alpha + \frac{\beta}{n}k\right)^z \left[1 - \Phi\left(\alpha + \frac{\beta}{n}k\right)\right]^{1-z}}{\Phi\left(\frac{\alpha + \beta\mu}{\sqrt{1 + \beta^2/n}}\right)^z \left[1 - \Phi\left(\frac{\alpha + \beta\mu}{\sqrt{1 + \beta^2/n}}\right)\right]^{1-z}}$$

$$N = n : \begin{cases} \ell(\mu) = -\frac{1}{2} \sum_{i=1}^N (y_i - \mu)^2 - \ln \Phi(\nu) \\ S(\mu) = \sum_{i=1}^N (y_i - \mu) - \tilde{\beta} \cdot \frac{\phi(\nu)}{\Phi(\nu)} \\ H(\mu) = -N + \tilde{\beta}^2 \cdot [\nu \cdot \Phi(\nu) + \phi(\nu)] \cdot \frac{\phi(\nu)}{\Phi(\nu)^2} \end{cases}$$

$$N = 2n : \begin{cases} \ell(\mu) = -\frac{1}{2} \sum_{i=1}^N (y_i - \mu)^2 - \ln [1 - \Phi(\nu)] \\ S(\mu) = \sum_{i=1}^N (y_i - \mu) + \tilde{\beta} \cdot \frac{\phi(\nu)}{1 - \Phi(\nu)} \\ H(\mu) = -N - \tilde{\beta}^2 \cdot \{\nu \cdot [1 - \Phi(\nu)] - \phi(\nu)\} \cdot \frac{\phi(\nu)}{[1 - \Phi(\nu)]^2} \end{cases}$$

# Information, Bias, MSE

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- Notation:

$$\tilde{\alpha} = \alpha / \sqrt{1 + \beta^2/n}$$

$$\tilde{\beta} = \beta / \sqrt{1 + \beta^2/n}$$

$$\nu = (\alpha + \beta\mu) / \sqrt{1 + \beta^2/n}$$

- Information:

$$I(\mu) = n[2 - \Phi(\tilde{\alpha} + \tilde{\beta}\mu)]$$

$$I_c(\mu) = n[2 - \Phi(\tilde{\alpha} + \tilde{\beta}\mu)] - \frac{\tilde{\beta}^2 \phi(\tilde{\alpha} + \tilde{\beta}\mu)^2}{\Phi(\tilde{\alpha} + \tilde{\beta}\mu)[1 - \Phi(\tilde{\alpha} + \tilde{\beta}\mu)]}$$

- **Counterintuitive?**  $N$  is not ancillary

- Some limits:

$$\beta = 0 \quad \implies \quad I(\mu) \equiv I_c(\mu)$$

$$n \longrightarrow \infty \quad \implies \quad I(\mu) = I_c(\mu)$$

- Both estimators asymptotically unbiased
- The conditional score  $E[S_c(\mu)] = 0$ :  
conditional likelihood estimator unbiased in finite samples

- Mean squared error

▷  $\beta < +\infty$ :

$$\text{MSE}(\hat{\mu}) = \frac{1}{n[2 - \Phi(\nu)]} + \frac{1}{4n^2}\tilde{\beta}^2\phi(\nu)^2$$

$$\text{MSE}(\hat{\mu}_c) \simeq \frac{1}{n[2 - \Phi(\nu)]} + \frac{1}{[2 - \Phi(\nu)]^2\Phi(\nu)[1 - \Phi(\nu)]n^2}\tilde{\beta}^2\phi(\nu)^2$$

▷  $\beta \rightarrow +\infty$ :

$$\text{MSE}(\hat{\mu}) = \frac{1}{n[2 - \Phi(\sqrt{n}\mu)]} + \frac{1}{4n}\phi(\sqrt{n}\mu)^2$$

$$\text{MSE}(\hat{\mu}_c) \simeq \frac{1}{n[2 - \Phi(\sqrt{n}\mu)]} + \frac{1}{[2 - \Phi(\sqrt{n}\mu)]^2\Phi(\sqrt{n}\mu)[1 - \Phi(\sqrt{n}\mu)]n}\phi(\sqrt{n}\mu)^2$$

# Likelihood Estimators: Conditional Bias

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- Conditional likelihood estimator: conditionally unbiased
- Joint likelihood estimator ( $\beta < +\infty$ ):

$$E(\bar{\mu}|N = n) = \mu + \frac{\beta}{\sqrt{1 + \beta^2/n}} \cdot \frac{\phi(\nu)}{n\Phi(\nu)}$$

$$E(\bar{\mu}|N = 2n) = \mu - \frac{\beta}{\sqrt{1 + \beta^2/n}} \cdot \frac{\phi(\nu)}{2n[1 - \Phi(\nu)]}$$

- Joint likelihood estimator ( $\beta \rightarrow +\infty$ ):

$$E(\bar{\mu}|N = n) = \mu + \frac{\phi(\sqrt{n}\mu)}{\sqrt{n}\Phi(\sqrt{n}\mu)}$$

$$E(\bar{\mu}|N = 2n) = \mu - \frac{\phi(\sqrt{n}\mu)}{2\sqrt{n}[1 - \Phi(\sqrt{n}\mu)]}$$

•  $\beta \rightarrow +\infty$  &  $n \rightarrow +\infty$ :

▷  $\mu < 0$

$$E(\bar{\mu}|N = n) \rightarrow 0$$

$$E(\bar{\mu}|N = 2n) \rightarrow \mu$$

▷  $\mu > 0$

$$E(\bar{\mu}|N = n) \rightarrow \mu$$

$$E(\bar{\mu}|N = 2n) \rightarrow \frac{\mu}{2}$$

▷ **Yet: asymptotically unbiased**



# Lack of Incompleteness $\rightarrow$ Counterintuitive Results

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- $N$  fixed  $\implies K$  complete

- Nice results apply

- **Lehmann-Scheffé theorem:**

unbiased

complete

sufficient

}

$\implies$

best mean-unbiased

- **Basu's theorem:**

complete  
sufficient }  $\implies$  independent of any ancillary statistic

- **Not** so in our case!

- Sufficient statistic is  $(N, K)$

- Joint distribution:

$$p_{\mu}(N, k) = p_0(N, k) \cdot \exp\left(k\mu - \frac{1}{2}n\mu^2\right)$$

$$p_0(n, k) = \phi_n(k) \cdot \Phi\left(\alpha + \frac{\beta}{n}k\right)$$

$$p_0(2n, k) = \phi_{2n}(k) \cdot \left[1 - \Phi\left(\frac{\alpha + \frac{\beta k}{2n}}{\sqrt{\frac{2n + \beta^2}{2n}}}\right)\right]$$

- To establish incompleteness, we must find a function  $g(k, N)$  satisfying:

$$g(k, 2n) \cdot p_0(2n, k) = - \int \phi_n(k - z) \cdot g(z, n) \cdot \phi_n(z) \cdot \Phi\left(\alpha + \frac{\beta}{n}z\right) dz$$

- Example:

$$g(k, n) = \frac{\ell}{\Phi\left(\alpha + \frac{\beta}{n}k\right)}$$

$$g(k, 2n) = \frac{\ell}{1 - \Phi\left(\frac{\alpha + \frac{\beta k}{2n}}{\sqrt{\frac{2n + \beta^2}{2n}}}\right)}$$

# Ordinary Sample Average is Biased and Not Optimal

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- Generalized sample average:

$$\bar{\mu} = \frac{K}{N} \cdot [c \cdot I(N = n) + d \cdot I(N = 2n)]$$

- Expectation:

$$E(\bar{\mu}) = d\mu + (c - d)\mu\Phi(\nu) + \frac{2c - d}{2n} \frac{\beta}{\sqrt{1 + \beta^2/n}} \cdot \phi(\nu)$$

# Generalized Sample Size

$\beta = 0$  — completely random sample size

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- A family of unbiased estimators:

$$d = \frac{1 - c\Phi}{1 - \Phi} \quad \implies \quad E(\bar{\mu}) = \mu$$

- Minimum variance:

$$c_{\text{opt}} = 1 - \frac{1}{2n} \cdot \frac{1 - \Phi}{\mu^2 + \frac{2 - \Phi}{2n}}, \quad d_{\text{opt}} = 1 + \frac{1}{2n} \cdot \frac{\Phi}{\mu^2 + \frac{2 - \Phi}{2n}}.$$

- **No uniform optimum**
- **Ordinary sample average is not optimal**

# Generalized Sample Size

$\beta \neq 0$  — stopping rule

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- All generalized sample averages **biased**
- This includes ordinary sample average!
- Asymptotically unbiased (as we know from likelihood)

# Generalization 1: Arbitrary Number of Looks

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- Our stopping rule

$$\Phi\left(\alpha + \frac{\beta}{n}k\right)$$

for  $\beta \rightarrow +\infty$  can be generalized to arbitrary numbers of looks

$$n_1 < n_2 < \dots < n_L$$

by applying

$$\Phi\left(\alpha_j + \frac{\beta_j}{n_j}k\right)$$

- Results carry over



# Generalization 2: Completely Random Sample Size

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- Allow for sample sizes with probabilities

$n$	$0$	$1$	$\dots$	$m$
$\pi_n$	$\pi_0$	$\pi_1$	$\dots$	$\pi_m$

- Incomplete sufficient statistic:

$$g(z, n) = b_n$$

$$\sum_{n=0}^m \pi_n \cdot b_n = 0$$

- Generalized sample average:

$$\bar{\mu} = \sum_{n=0}^m \frac{K}{n} \cdot a_n \cdot I(N = n)$$

- **Unbiased** generalized sample average:

$$a_n = 1 + b_n$$

- Optimal estimator:

$$a_n = \frac{1}{\sum_{k=0}^m \frac{\pi_k}{\mu^2 + \sigma^2/k}}$$

# Generalization 3: Missing Data

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- Our stopping rule

$$\Phi\left(\alpha + \frac{\beta}{n}k\right)$$

for  $0 < \beta < +\infty$  corresponds to MAR missingness **in independent data**

- Can be generalized to longitudinal sequences

Joint likelihood  $\equiv$  selection model representation

Conditional likelihood  $\equiv$  pattern-mixture model

- Assume, for example

$$\mathbf{Y}_i = (\mathbf{Y}_{i1}, \mathbf{Y}_{i2})$$

- ▷ first block always observed
- ▷ second one possibly missing

- Sample average is **not** an option:

$$\widehat{\boldsymbol{\mu}}_1 = \frac{1}{N} \sum_{i=1}^N \mathbf{y}_{i1}$$

$$\widehat{\boldsymbol{\mu}}_2 = \frac{1}{n} \sum_{i=1}^n \mathbf{y}_{i2} - \boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} \left( \frac{1}{n} \sum_{i=1}^n \mathbf{y}_{i1} - \frac{1}{N} \sum_{i=1}^N \mathbf{y}_{i1} \right)$$

# Generalization 4: Informative Cluster Sizes

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- **Either:** Model for two random variables:
  - ▷ Outcomes  $Y_i$
  - ▷ Cluster size  $t_i$
- **Or:** model for three random variables:
  - ▷ Outcomes  $Y_i$
  - ▷ Observed cluster size  $t_i$
  - ▷ Theoretical cluster size  $n_i \geq t_i$
- Entirely similar to missing-data setting

# Generalization 5: Joint Model for Longitudinal and Survival Data

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- Model for two, three, or four random variables:
  - ▷ Longitudinal process  $Y_i$
  - ▷ Time-to-event outcome  $T_i$
  - ▷ Censoring time  $C_i$
  - ▷ Missing data process  $R_i$
- Formulate an appropriate “shared-parameter model”
- Results carry over

# Conclusions

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- Commonality across seemingly unrelated settings
- Ordinary sample average loses its 'perfect status' ← lack of **completeness**
  - ▷ Already with completely random sample size
  - ▷ More so with deterministic or probabilistic stopping rule
- It nevertheless is a **valid estimator**:
  - ▷ Asymptotically unbiased (unbiased for CRSS)
  - ▷ Almost optimal
  - ▷ Asymptotically optimal
  - ▷ Consistent with the likelihood