AN ASYMPTOTIC STUDY OF VARIABLE BANDWIDTH SELECTION FOR LOCAL POLYNOMIAL REGRESSION WITH APPLICATION TO DENSITY ESTIMATION

by

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An Asymptotic Study of Variable Bandwidth Selection for Local Polynomial Regression with Application to Density Estimation

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Abstract

A decisive question in nonparametric smoothing techniques is the choice of the bandwidth or smoothing parameter. The present paper addresses this question when using local polynomial approximations for estimating the regression function and its derivatives. A fully-automatic bandwidth selection procedure has been proposed by Fan and Gijbels (1993), and the empirical performance of it was tested in detail via a variety of examples. Those experiences supported the methodology towards a great extend. In this paper we establish asymptotic results for the proposed variable bandwidth selector. We provide the rate of convergence of the bandwidth estimate, and obtain the asymptotic distribution of its error relative to the theoretical optimal variable bandwidth. Those asymptotic properties give extra support to the developed bandwidth selection procedure. It is also demonstrated how the proposed selection method can be applied in the density estimation setup. Some examples illustrate this application.

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1 Introduction

In this paper primary interest focuses on studying the regression relationship between two variables X and Y. In nonparametric estimation no prior assumption is made about the form of the regression function: the data itself will determine this form. Various smoothing techniques can be used to detect the underlying structure, but each of them involve the decisive choice of a smoothing parameter or bandwidth. In this paper we discuss how to choose a bandwidth when local polynomial fitting is used. It was shown extensively in the literature that the local polynomial approximation method has various nice features, among which, nice minimax properties, satisfactory boundary behavior, applicability for a variety of design-situations and easy interpretability. See, for example, Stone (1977), Fan (1992, 1993), Fan and Gijbels (1992), Ruppert and Wand (1992) and Fan et. al (1993). The papers by Cleveland (1979) and Cleveland and Devlin (1988) contain ample of nice examples, in various fields of applications, illustrating the performance of locally-weighted regression. Hastie and Tibshirani (1986) discussed the particular class of locally-weighted running-line smoothers.

Assume that the bivariate data $(X_1, Y_1), \ldots, (X_n, Y_n)$ form an i.i.d. sample from the model

$$Y = m(X) + \sigma(X)\varepsilon, \qquad E\varepsilon = 0 \qquad \text{and} \qquad \text{Var}(\varepsilon) = 1,$$

where X and ε are independent random variables. The objective is to estimate the regression function $m(x) = E(Y|X = x)$ and its derivatives, based on the observations $(X_1, Y_1), \cdots, (X_n, Y_n)$. The marginal density of X will be denoted by $f_X(\cdot)$. The above location-scale model is not a necessity, but a convenient way to introduce the notations. The i.i.d. assumption on the bivariate data suffices.

Suppose that the $(p+1)^{th}$-derivative of $m(x)$ at the point x_0 exists. We then approximate $m(x)$ locally by a polynomial of order p:

$$m(x) \approx m(x_0) + m'(x_0)(x - x_0) + \cdots + m^{(p)}(x_0)(x - x_0)^p/p!, \tag{1.1}$$

for x in a neighborhood of x_0, and do a local polynomial regression fit

$$\min_{\beta} \sum_{i=1}^{n} \left(Y_i - \sum_{j=0}^{p} \beta_j (X_i - x_0)^j \right)^2 K\left(\frac{X_i - x_0}{h} \right), \tag{1.2}$$

where $\beta = (\beta_0, \cdots, \beta_p)^T$. Here $K(\cdot)$ denotes a nonnegative weight function and h is a smoothing parameter — determining the size of the neighborhood of x_0. Let $\{\hat{\beta}_\nu\}$ denote the solution to the weighted least squares problem (1.2). Then it is obvious from the Taylor expansion in (1.1) that $\nu!\hat{\beta}_\nu$ estimates $m^{(\nu)}(x_0), \nu = 0, \cdots, p$.

For convenience we introduce some matrix notations. Let $\mathbf{W}$ be the diagonal matrix of weights, with entries $W_i \equiv K\left(\frac{X_i - x_0}{h}\right)$. Denote by $\mathbf{X}$ the design matrix whose $(l, j)^{th}$ element is $(X_l - x_0)^{j-1}$ and put $\mathbf{y} = (Y_1, \cdots, Y_n)^T$. Then, the weighted least squares problem (1.2) reads as follows:

$$\min_{\beta} (\mathbf{y} - \mathbf{X}\beta)^T \mathbf{W} (\mathbf{y} - \mathbf{X}\beta).$$

The solution vector is provided via ordinary least squares and is given by

$$\hat{\beta} = (\mathbf{X}^T \mathbf{W} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{W} \mathbf{y}. \tag{1.3}$$

An important issue for the performance of the estimator $\hat{\beta}_\nu$ is the choice of the smoothing parameter h. A constant bandwidth can be sufficient if the unknown regression function behaves quite smoothly. In other situations a local variable bandwidth (which changes with the location point x_0) is a necessity. The problem of choosing a smoothing parameter received a lot of attention in the literature. Müller and Stadtmüller (1987) studied the choice of a local variable bandwidth for convolution type estimators of regression curves. Data-driven bandwidth selection rules based on "plug-in" techniques were considered in Gasser, Kneip and Köhler (1991), Sheather and Jones (1991), Hall, Sheather, Jones and Marron (1991) and Brockmann et al. (1993). See also Vieu (1991) and Ruppert, Sheather and Wand (1993). An interesting survey on recent developments in bandwidth selection is given in Jones, Marron and Sheather (1992).

Fan and Gijbels (1993) developed an appealing bandwidth selection procedure for local polynomial regression. The basic ideas for their procedure is to assess the Mean Squared

Error (MSE) of the estimators via deriving good finite sample estimates of this theoretical MSE. See also Section 2. The performance of the selection methodology was investigated in detail via simulation studies. In the present paper we provide further theoretical foundations for the proposed bandwidth selection rule. More precisely, we establish the rate of convergence of the bandwidth selector as well as the asymptotic distribution of its error relative to the theoretical optimal variable bandwidth. Furthermore, we show how to convert a density estimation problem into a regression problem. This inner connection makes it possible to apply the regression techniques for density estimation.

The organization of the paper is as follows. In the next section, we explain briefly the bandwidth selection rule and present the obtained asymptotic results for the estimated optimal bandwidth. In Section 3 we discuss how the bandwidth selection procedure can be applied in density estimation. Some examples illustrate the application in this setup. The last section contains the proofs of the theoretical results established in Section 2.

2 Bandwidth selection method and main results

Let $\hat{\beta}$ be the vector of local polynomial regression estimates, defined in (1.3). Clearly, its bias and variance, conditionally upon $\underset{\sim}{X} = \{X_1, \cdots, X_n\}$, are given by

$$\begin{aligned} \text{Bias}(\hat{\beta}|\underset{\sim}{X}) &= \text{E}(\hat{\beta}|\underset{\sim}{X}) - \beta = (\mathbf{X}^T\mathbf{W}\mathbf{X})^{-1}\mathbf{X}^T\mathbf{W}(\mathbf{m} - \mathbf{X}\beta) \\ \text{Var}(\hat{\beta}|\underset{\sim}{X}) &= (\mathbf{X}^T\mathbf{W}\mathbf{X})^{-1}(\mathbf{X}^T\Sigma\mathbf{X})(\mathbf{X}^T\mathbf{W}\mathbf{X})^{-1}, \end{aligned} \tag{2.1}$$

where $\mathbf{m} = (m(X_1), \ldots, m(X_n))^T$, and $\Sigma = \text{diag}\left(K^2(\frac{X_i - x_0}{h})\sigma^2(X_i)\right)$.

Note that the expressions in (2.1) give the exact bias and variance of the local polynomial fit. We next study asymptotic expansions of this bias vector and variance matrix. These expansions serve as a gateway to prove the asymptotic normality of the selected bandwidth. The following assumptions will be needed.

Assumptions:

(i) The kernel K is a bounded and continuous density function with finite $(2p+5)^{th}$

moment;

(ii) $f_X(x_0) > 0$ and $f_X''(x)$ is bounded in a neighborhood of x_0;

(iii) $m^{(p+3)}(\cdot)$ exists and is continuous in a neighborhood of x_0;

(iv) $\sigma^2(\cdot)$ has a bounded second derivative in a neighborhood of x_0;

(v) $m^{(p+1)}(x_0) \neq 0$ and the kernel K is symmetric.

In the sequel we will use the following notations. Let $\mu_j = \int u^j K(u)du$ and $\nu_j = \int u^j K^2(u)du$ and denote

$$S_p = (\mu_{i+j-2})_{1\leq i,j\leq(p+1)}\,, \qquad \tilde{S}_p = (\mu_{i+j-1})_{1\leq i,j\leq(p+1)}.$$
$$S_p^* = (\nu_{i+j-2})_{1\leq i,j\leq(p+1)}\,, \qquad \tilde{S}_p^* = (\nu_{i+j-1})_{1\leq i,j\leq(p+1)}.$$

Further, set $c_p = (\mu_{p+1},\ldots,\mu_{2p+1})^T$ and $\tilde{c}_p = (\mu_{p+2},\ldots,\mu_{2p+2})^T$.

The asymptotic expansions for the conditional bias and variance are provided in the next theorem.

Theorem 1. *Under Assumptions (i) — (iv), the bias vector and variance matrix of $\hat{\beta}$ have the following expansions:*

$$Bias(\hat{\beta}|\underset{\sim}{X}) = h^{p+1}H^{-1}\left[\beta_{p+1}S_p^{-1}c_p + h\,b^*(x_0) + O_P\left(h^2 + \frac{1}{\sqrt{nh}}\right)\right] \tag{2.2}$$

and

$$Var(\hat{\beta}|\underset{\sim}{X}) = \frac{\sigma^2(x_0)}{f_X(x_0)nh}H^{-1}\left[S_p^{-1}S_p^*S_p^{-1} + h\,V^*(x_0) + O_P\left(h^2 + \frac{1}{\sqrt{nh}}\right)\right]H^{-1}, \tag{2.3}$$

where $H = diag(1,h,\ldots,h^p)$,

$$b^*(x_0) = \frac{f_X'(x_0)\beta_{p+1} + \beta_{p+2}f_X(x_0)}{f_X(x_0)}S_p^{-1}\tilde{c}_p - \frac{f_X'(x_0)}{f_X(x_0)}\beta_{p+1}S_p^{-1}\tilde{S}_pS_p^{-1}c_p,$$

and

$$\begin{aligned} V^*(x_0) \;=\; & \frac{2\sigma'(x_0)f_X(x_0) + \sigma(x_0)f_X'(x_0)}{\sigma(x_0)f_X(x_0)}S_p^{-1}\tilde{S}_p^*S_p^{-1} \\ & -\frac{f_X'(x_0)}{f_X(x_0)}\left(S_p^{-1}\tilde{S}_pS_p^{-1}S_p^*S_p^{-1} + S_p^{-1}S_p^*S_p^{-1}\tilde{S}_pS_p^{-1}\right). \end{aligned}$$

Remark 1. For a symmetric kernel K, we will show in the proof of Theorem 2 that the $(\nu+1)^{th}$-diagonal element of $V^*(x_0)$ and the $(\nu+1)^{th}$-element of $b^*(x_0)$ (with $p-\nu$ odd) are zero. In other words, if $p-\nu$ is odd, the second leading terms in the expansions of the bias and variance of $\hat{\beta}_\nu$ are zero. The requirement for odd $p-\nu$ is natural, since the odd order approximations outperform the even order ones, as demonstrated in Ruppert and Wand (1992) and Fan and Gijbels (1993).

Based on Theorem 1, we can derive the rate of convergence for bandwidth selection. We need the following simple lemma.

Lemma 1. *Suppose that a function $M(h)$ has the following asymptotic expansion:*

$$M(h) = ah^{2(p+1-\nu)}\left(1+O_P(h^2+\frac{1}{\sqrt{nh}})\right)+\frac{b}{nh^{2\nu+1}}\left(1+O_P(h^2+\frac{1}{\sqrt{nh}})\right) \qquad as\ h\to 0.$$

Let h_{opt} be the minimizer of $M(h)$. Then

$$h_{opt}=\left(\frac{(2\nu+1)b}{2(p+1-\nu)a\,n}\right)^{\frac{1}{2p+3}}\left(1+O_P\left(n^{-\frac{2}{2p+3}}\right)\right),$$

and

$$M(h_{opt})=a^{1-s}b^s(2p+3)(2\nu+1)^{-(1-s)}[2(p+1-\nu)]^{-s}n^{-s}\left(1+O_P\left(n^{-\frac{2}{2p+3}}\right)\right),$$

provided that $a,\ b>0$, and with $s=\frac{2(p+1-\nu)}{2p+3}$.

We now study the theoretical optimal variable bandwidth for estimating the ν^{th}-derivative $m^{(\nu)}(x_0)$. Let

$$\mathrm{MSE}_\nu(x_0)=b_{p,\nu}^2(x_0)+V_{p,\nu}(x_0),$$

where $b_{p,\nu}(x_0)$ and $V_{p,\nu}(x_0)$ are respectively the $(\nu+1)^{th}$-element of $\mathrm{Bias}(\hat{\beta}|\underset{\sim}{X})$ and the $(\nu+1)^{th}$-diagonal element of $\mathrm{Var}(\hat{\beta}|\underset{\sim}{X})$. Define

$$h_{\nu,opt}=\arg\min_h \mathrm{MSE}_\nu(x_0).$$

The quantity $\mathrm{MSE}_\nu(x_0)$ is, in a sense, an ideal assess of the MSE of $\hat{\beta}_\nu$, and $h_{\nu,opt}$ is the ideal bandwidth selector.

We have the following expression for this ideal optimal bandwidth.

Theorem 2. *Under Assumptions (i) — (v) it holds that*

$$\frac{h_{\nu,opt} - h_o}{h_o} = O_P(n^{-\frac{2}{2p+3}})$$

provided that $p - \nu$ is odd, where

$$h_o = \left(\frac{(2\nu+1)\sigma^2(x_0) e_{\nu+1}^T S_p^{-1} S_p^* S_p^{-1} e_{\nu+1}}{2(p+1-\nu) f_X(x_0) (\beta_{p+1} e_{\nu+1}^T S_p^{-1} c_p)^2 \, n} \right)^{\frac{1}{2p+3}}. \tag{2.4}$$

Here, $e_{\nu+1}$ denotes the $(p+1) \times 1$ unit vector, containing 1 on the $(\nu+1)^{th}$-position.

We next briefly motivate a natural estimator for assessing the bias and the variance in (2.1). Using a Taylor expansion around the point x_0, we have

$$\mathbf{m} - \mathbf{X}\beta \approx \left(\beta_{p+1}(X_i - x_0)^{p+1} \right)_{1 \le i \le n}, \quad \text{and} \quad \sigma(X_i) \approx \sigma(x_0).$$

Substituting this into (2.1) leads to

$$\begin{aligned} \text{Bias}(\hat{\beta}|\underset{\sim}{X}) &\approx \beta_{p+1} S_n^{-1} \left(s_{n,p+1}, \ldots, s_{n,2p+1}\right)^T \\ \text{Var}(\hat{\beta}|\underset{\sim}{X}) &\approx \sigma(x_0) S_n^{-1} (\mathbf{X}\mathbf{W}^2\mathbf{X}) S_n^{-1}, \end{aligned} \tag{2.5}$$

where

$$s_{n,j} = \sum_{i=1}^{n} (X_i - x_0)^j K\left(\frac{X_i - x_0}{h}\right) \text{ and } S_n = \mathbf{X}^T\mathbf{W}\mathbf{X} = (s_{n,i+j-2})_{1 \le i,j \le (p+1)}.$$

A natural estimate of the bias and the variance is obtained by estimating β_{p+1} and $\sigma^2(x_0)$ in (2.5) from another least squares problem.

Let β_{p+1} be estimated by using a local polynomial regression of order r $(r > p)$ with a bandwidth h_*. Further, estimate $\sigma^2(x_0)$ by the standardized residual sum of squares:

$$\hat{\sigma}^2(x_0) = \frac{1}{\text{tr}(\mathbf{W}^*) - \text{tr}\left((\mathbf{X}^{*T}\mathbf{W}^*\mathbf{X}^*)^{-1} \mathbf{X}^* \mathbf{W}^{*2} \mathbf{X}^* \right)} \sum_{i=1}^{n} (Y_i - \hat{Y}_i)^2 K\left(\frac{X_i - x_0}{h_*}\right),$$

where $\mathbf{X}^* = \left((X_i - x_0)^j\right)_{n \times (r+1)}$ is the design matrix, $\mathbf{W}^* = \text{diag}\left(K(\frac{X_i - x_0}{h_*})\right)$ is the matrix of weights and $\hat{\mathbf{y}} = \mathbf{X}^*(\mathbf{X}^{*T}\mathbf{W}\mathbf{X}^*)^{-1}\mathbf{X}^{*T}\mathbf{W}^*\mathbf{y}$ is the vector of "predicted" values after the local r^{th}-order polynomial fit. The estimated MSE of $\hat{\beta}_\nu$ is naturally defined by

$$\widehat{\text{MSE}}_\nu(x_0) = \hat{b}_{p,\nu}^2(x_0) + \hat{V}_{p,\nu}(x_0),$$

where $\hat{b}_{p,\nu}(x_0)$ and $\hat{V}_{p,\nu}(x_0)$ are respectively the $(\nu+1)^{th}$-element of the bias vector and the $(\nu+1)^{th}$-diagonal element of the variance matrix in (2.5), with β_{p+1} and $\sigma(x_0)$ being estimated. More precisely, $\hat{b}_{p,\nu}(x_0)$ refers to the $(\nu+1)^{th}$-element of $\hat{\beta}_{p+1} S_n^{-1} \, (s_{n,p+1}, \ldots, s_{n,2p+1})^T$ and $\hat{V}_{p,\nu}(x_0)$ is the $(\nu+1)^{th}$-diagonal element of $\hat{\sigma}^2(x_0) \; S_n^{-1} \; (\mathbf{X}^T \mathbf{W}^2 \mathbf{X}) \; S_n^{-1}$.

Define the estimated optimal bandwidth as

$$\hat{h}_\nu = \arg\min_h \widehat{\mathrm{MSE}}_\nu(x_0).$$

We now study the sampling properties of $\hat{h}_\nu$. Using the arguments provided in Theorems 1 and 2 on the set $\{|\hat{\beta}_{p+1}| \leq c, |\hat{\sigma}(x_0)| \leq c\}$, where c is a large constant, we find that

$$\frac{\hat{h}_\nu - \hat{h}_o}{\hat{h}_o} = O_P(n^{-\frac{2}{2p+3}}), \tag{2.6}$$

where $\hat{h}_o$ is defined similarly as h_o in equation (2.4), but now with β_{p+1}, respectively $\sigma^2(x_0)$, replaced by $\hat{\beta}_{p+1}$, respectively $\hat{\sigma}^2(x_0)$.

Using equation (2.6) and Theorem 2, we obtain

$$\frac{\hat{h}_\nu - h_{\nu,opt}}{h_{\nu,opt}} = \frac{\hat{h}_o - h_o}{h_o} + O_P(n^{-\frac{2}{2p+3}}),$$

and the following lemma.

Lemma 2. *If the estimators $\hat{\beta}_{p+1}$ and $\hat{\sigma}^2(x_0)$ are stochastically bounded away from zero and infinity, then we have for the relative error*

$$\frac{\hat{h}_\nu - h_{\nu,opt}}{h_{\nu,opt}} = \frac{(\hat{\sigma}^2(x_0)/\sigma^2(x_0))^{\frac{1}{2p+3}} - (\hat{\beta}_{p+1}^2/\beta_{p+1}^2)^{\frac{1}{2p+3}}}{(\hat{\beta}_{p+1}^2/\beta_{p+1}^2)^{\frac{1}{2p+3}}} + O_P(n^{-\frac{2}{2p+3}}.)$$

Remark 2. Lemma 2 holds for any estimators $\hat{\beta}_{p+1}$ and $\hat{\sigma}^2(x_0)$ which are stochastically bounded away from zero and infinity. So, these estimators should not necessarily be obtained via local polynomial fitting.

In order to discuss the asymptotic distribution of $\frac{\hat{h}_\nu - h_{\nu,opt}}{h_{\nu,opt}}$, we make some further assumptions.

Assumptions:

(vi) $E(\varepsilon^4) < \infty$;

(vii) The bandwidth h_* satisfies $n^{-\frac{1}{2p+3}} << h_* << n^{-\frac{2p-1}{(2p+3)^2}}$.

Remark that $\hat{\sigma}^2(x)$ converges to $\sigma^2(x)$ much faster than $\hat{\beta}_{p+1}$ to β_{p+1}. Thus, it follows from Lemma 2 that the behavior of $\hat{\beta}_{p+1}$ dictates that of the relative error. For this reason, we introduce the following notations. Let α be the $(p+2)^{th}$-element of the vector $S_r^{-1}c_r$ and γ be the $(p+2)^{th}$-diagonal element of the matrix $S_r^{-1}S_r^*S_r^{-1}$. Remark that α and γ are the constant factors in the asymptotic bias and variance expressions of $\hat{\beta}_{p+1}$ using the local r^{th}-order polynomial regression.

Theorem 3. *Suppose that $p-\nu$ is odd. Then, under Assumptions (i)- (vii),*

$$\sqrt{nh_*^{2p+3}}\left(\frac{\hat{h}_\nu - h_{\nu,opt}}{h_{\nu,opt}} + \frac{2\alpha\beta_{r+1}}{(2p+3)\beta_{p+1}}h_*^{r-p}\right) \xrightarrow{D} N(0, \frac{4\gamma\sigma^2(x_0)}{(2p+3)^2\beta_{p+1}^2 f_X(x_0)}). \qquad (2.7)$$

Remark 3. The asymptotic distribution of the relative error is independent of ν. When $r = p+2$, and $h_* \sim n^{-\frac{1}{2r+3}}$, the relative error is of order $O_P(n^{-\frac{2}{2r+3}})$.

In Theorem 3 we do not specify a method for selecting h_*. A data-driven procedure for choosing h_* is provided in Fan and Gijbels (1993) via an ECV-criteria. See that paper for details of the particular criteria, as well as for details on the implementation of selecting a variable bandwidth.

3 Application to Density Estimation

The bandwidth selection procedure for the regression problem can also be applied to the density estimation setup. Let $X_1, \ldots, X_n$ be independent identically distributed random variables. The interest is to estimate the common density $f(x)$ and its derivatives on an interval $[a,b]$. Partition the interval $[a,b]$ into N subintervals $\{I_k, k = 1, \ldots, N\}$. Let x_k be the center of I_k and y_k be the proportion of data $\{X_i, i = 1, \ldots, n\}$, falling in the partition I_k, divided by the bin length. Then, we use a local polynomial of order p to fit the data

$\{(x_k, y_k), k = 1, \ldots, N\}$. Let $\hat{\beta}_0, \ldots, \hat{\beta}_p$ be the solution of the local polynomial regression problem:

$$\sum_{k=1}^{N} (y_k - \sum_{j=0}^{p} \beta_j (x_k - x)^j)^2 K\left(\frac{x_k - x}{h}\right).$$

Then, the estimator for the ν^{th} derivative is

$$\hat{f}^{(\nu)}(x) = \nu! \hat{\beta}_\nu.$$

In order to have the same asymptotic properties for $\hat{f}^{(\nu)}(x)$ as those available for the kernel density estimator, we require that

$$Nh \longrightarrow \infty$$

(see Cheng, Fan, and Marron (1993)). Now, the bandwidth selection procedure discussed in the previous section can also be applied to this setting. We would expect the resulting bandwidth selector to have the following property (compare with (2.7)):

$$\sqrt{n h_*^{2p+3}} \left(\frac{\hat{h}_\nu - h_{\nu,opt}}{h_{\nu,opt}} + \frac{2\alpha(p+1)! f^{(r+1)}(x)}{(2p+3)(r+1)! f^{(p+1)}(x)} h_*^{r-p} \right)$$
$$\xrightarrow{D} N\left(0, \frac{4\gamma}{(2p+3)^2 (f^{(p+1)}(x)/(p+1)!)^2}\right).$$

We now illustrate the data-driven density estimation procedure via four simulated examples. These four densities were chosen from the 15 normal mixture densities discussed in Marron and Wand (1992). They were recommended by J.S. Marron in a private conversation, on the ground that they range from densities easy to estimate to densities very hard to estimate. In the implementation, we took $N = n/4$ and used Anscombe's (1948) variance-stabilizing transformation to the bin count $c_k = n\ y_k \times$ length(I_k):

$$y_k^* = 2\sqrt{c_k + \frac{3}{8}}.$$

Let $\hat{\beta}_0^*$ be the local linear regression smoother for the transformed data. Then the density estimator is obtained by considering the inverse of Anscombe's transformation:

$$\hat{f}(x) = C \left(\frac{(\hat{\beta}_0^*)^2}{4} - \frac{3}{8} \right)_+,$$

where the constant C is a normalization constant such that $\hat{f}(x)$ has area 1. This transformation step stabilized our simulation results somewhat, but did not result into a significant improvement. The variable bandwidth is, as described above, selected by using the techniques developed in Fan and Gijbels (1993) for the regression setup. Another possible, but more complicated, way of converting the density estimation problem into a regression problem is given in Wei and Chu (1993). We have no intention to recommend the scientific community to use regression techniques for density estimation. Here, we only point out the inner connection between nonparametric regression and density estimation. This connection makes that nonparametric regression techniques such as data-driven bandwidth selection are also available for density estimation. These include procedures proposed by Gasser, Kneip and Köhler (1991) and those in Fan and Gijbels (1993) — in particular the constant bandwidth selection procedures such as ECV- and Refined bandwidth- selectors.

The four simulated examples concern a Gaussian density, a Strongly Skewed density, a Separated Bimodal density and a Smooth Comb density. Those correspond with respectively Densities #1, #3, #7 and #14 in Marron and Wand (1992). For each of the simulated examples we used the Epanechnikov kernel and estimated the density using a local linear approximation, based on samples of size 200 and 800. The number of simulations was 400. For each estimated curve we calculated the Mean Squared Error over all grid points in which the curve was evaluated. We then ranked the 400 estimated curves according to this global measure. As representatives of all estimated curves we took the curves corresponding to the 10^{th}%, the 50^{th}% and the 90^{th}% among those rank-observations. Each of the presented pictures contains the true density function (the solid line) and three typical estimated curves (other line types).

Put Figures 1.1 — 4.2 about here

Figures 1.1 and 1.2: *A Gaussian Density (solid curve) and three estimated curves (dashed lines), based on* $n = 200$, *respectively* $n = 800$.
Figures 2.1 and 2.2: *A Strongly Skewed Density (solid curve) and three estimated curves (dashed lines), based on* $n = 200$, *respectively* $n = 800$.
Figures 3.1 and 3.2: *A Separated Bimodal Density (solid curve) and three estimated*

curves (dashed lines), based on n = 200, respectively n = 800.
Figures 4.1 and 4.2: *A Smooth Comb Density (solid curve) and three estimated curves (dashed lines), based on n = 200, respectively n = 800.*

The Gaussian density in Example 1 and the Separated Bimodal density in Example 3 are easiest to estimate, and hence estimates based on samples of size 200 show a good performance. The densities in Examples 2 and 4 (i.e. the Strongly Skewed density and the Smooth Comb density) form a more difficult task. Estimates based on samples of size 200 do not succeed in capturing the sharp peaks appearing in the densities. Samples of size 800 result into better estimated curves.

4 Proofs

Proof of Theorem 1. We first remark that

$$\begin{aligned} s_{n,j} &= \sum_{i=1}^{n}(X_i - x_0)^j K\left(\frac{X_i - x_0}{h}\right) \\ &= nh^{j+1}\int u^j K(u) f_X(x_0 + hu)du + O_P\left(\sqrt{nE\left[(X_1 - x_0)^{2j}K^2(\frac{X_1 - x_0}{h})\right]}\right) \\ &= nh^{j+1}\left(f_X(x_0)\mu_j + hf'_X(x_0)\mu_{j+1} + O_P(a_n)\right), \end{aligned} \tag{4.1}$$

where $a_n = h^2 + \frac{1}{\sqrt{nh}}$. Thus

$$S_n = nhH\left(f_X(x_0)S_p + hf'_X(x_0)\tilde{S}_p + O_P(a_n)\right)H. \tag{4.2}$$

It follows from equation (2.1) and Taylor's expansion that

$$\begin{aligned} &\text{Bias}(\hat{\beta}|\underset{\sim}{X}) \\ &= S_n^{-1}\mathbf{X}^T W\left(\beta_{p+1}(X_i - x_0)^{p+1} + \beta_{p+2}(X_i - x_0)^{p+2} + O_P\left((X_i - x_0)^{p+3}\right)\right)_{1\le i\le n} \\ &= S_n^{-1}\left(\beta_{p+1}c_n + \beta_{p+2}\tilde{c}_n + o_P(h^{p+3})\right), \end{aligned} \tag{4.3}$$

where $c_n = (s_{n,p+1}, \ldots, s_{n,2p+1})^T$ and $\tilde{c}_n = (s_{n,p+2}, \ldots, s_{n,2p+2})^T$. Combination of equations (4.2) and (4.3) leads to

$$\text{Bias}(\hat{\beta}|\underset{\sim}{X}) = H^{-1}\left(f_X(x_0)S_p + hf'_X(x_0)\tilde{S}_p + O_P(a_n)\right)^{-1}$$

$$\times h^{p+1}\left(\beta_{p+1}f_X(x_0)c_p + h\left(f'_X(x_0)\beta_{p+1} + \beta_{p+2}f_X(x_0)\right)\tilde{c}_p + O_P(a_n)\right). \tag{4.4}$$

Remark that

$$(A+hB)^{-1} = A^{-1} - hA^{-1}BA^{-1} + O(h^2). \tag{4.5}$$

Applying this to equation (4.4) and using some simple algebra, we obtain the bias expression (2.2) in Theorem 1.

For the variance matrix remark from (2.1) that

$$\mathrm{Var}(\hat{\beta}|\underset{\sim}{X}) = S_n^{-1}S_n^*S_n^{-1}, \tag{4.6}$$

where $S_n^* = (s^*_{n,i+j-2})_{1\le i,j\le(p+1)}$, with $s^*_{n,j} = \sum_{i=1}^{n}(X_i - x_0)^j K^2\left(\frac{X_i - x_0}{h}\right)\sigma^2(X_i)$. Following similar arguments as in (4.1) we find that,

$$s^*_{n,j} = nh^{j+1}\left(g(x_0)\nu_j + hg'(x_0)\nu_{j+1} + O_P(a_n)\right), \tag{4.7}$$

where $g(x_0) = f_X(x_0)\sigma^2(x_0)$. From (4.6), (4.7) and (4.2) we obtain that

$$\begin{aligned}\mathrm{Var}(\hat{\beta}|\underset{\sim}{X}) &= \frac{nhg(x_0)}{(f_X(x_0)nh)^2}H^{-1}\left(S_p + \frac{hf'_X(x_0)}{f_X(x_0)}\tilde{S}_p + O_P(a_n)\right)^{-1} \\ &\quad\times\left(S_p^* + h\frac{g'(x_0)}{g(x_0)}\tilde{S}_p^* + O_P(a_n)\right)\left(S_p + \frac{hf'_X(x_0)}{f_X(x_0)}\tilde{S}_p + O_P(a_n)\right)^{-1}H^{-1}.\end{aligned}$$

The conclusion in (2.3) now follows from equation (4.5) and some simple algebra. □

Proof of Lemma 1. Let

$$h_o = \left(\frac{(2\nu+1)b}{2(p+1-\nu)a\ n}\right)^{\frac{1}{2p+3}}.$$

Then

$$M(h_o) = a^{1-s}b^s(2p+3)(2\nu+1)^{-(1-s)}[2(p+1-\nu)]^{-s}n^{-s}(1+O_P(n^{-\frac{2}{2p+3}})).$$

It is easy to see that for any h such that $|h/h_o - 1| > Cn^{-\frac{2}{2p+3}}$, $M(h) > M(h_o)$ when C is large. In other words, such an h can not be a minimizer of $M(h)$. Hence $|h/h_o - 1| \le$

$Cn^{-\frac{2}{2p+3}}$. This proves the first conclusion. The second conclusion follows directly from the first. □

Proof of Theorem 2. Since the kernel K is symmetric, $\mu_{2j+1} = 0$, for $j = 0, 1, \ldots, (p+1)$. Thus, the matrix $S_p = (\mu_{i+j-2})_{1 \le i,j \le (p+1)}$ has the following structure:

$$S_p = \begin{pmatrix} \times & 0 & \times & 0 & \ldots \\ 0 & \times & 0 & \times & \ldots \\ \times & 0 & \times & 0 & \ldots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix},$$

where "×" denotes any number. It can be shown that S_p^{-1} will have exactly the same structure as S_p, by examining the determinant of the accompanying submatrix: this submatrix contains $[(p+1)/2]$ rows which each have at most $[(p+1)/2] - 1$ nonzero elements. Thus, these rows are linearly dependent and the determinant of the accompanying submatrix must be zero. Therefore, each odd-position (e.g. (3,4)) -element is zero. Similar arguments hold for the matrix

$$\tilde{S}_p = (\mu_{i+j-1})_{1 \le i,j \le (p+1)} = \begin{pmatrix} 0 & \times & 0 & \times & \ldots \\ \times & 0 & \times & 0 & \ldots \\ 0 & \times & 0 & \times & \ldots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}.$$

Using the sparsity structure of the matrices S_p and $\tilde{S}_p$, and of c_p and $\tilde{c}_p$, we can see that the $(\nu+1)^{th}$-element of $S_p^{-1}c_p$ and of $S_p^{-1}\tilde{S}_p S_p^{-1}c_p$ are zero. Thus by Theorem 1,

$$b_{p,\nu}(x_0) = \beta_{p+1} h^{p+1-\nu} e_{\nu+1}^T S_p^{-1} c_p \left(1 + O_P(h^2 + \frac{1}{\sqrt{nh}})\right). \tag{4.8}$$

A similar argument shows that the $(\nu+1)^{th}$-diagonal element of $V^*(x_0)$ in Theorem 1 is zero. Therefore, by Theorem 1,

$$V_{p,\nu}(x_0) = \frac{\sigma^2(x_0)}{f_X(x_0)nh} h^{-2\nu} e_{\nu+1}^T S_p^{-1} S_p^* S_p^{-1} e_{\nu+1} \left(1 + O_P(h^2 + \frac{1}{\sqrt{nh}})\right). \tag{4.9}$$

Combining equations (4.8) and (4.9) gives

$$\mathrm{MSE}_\nu(x_0) = \left(\beta_{p+1} e_{\nu+1}^T S_p^{-1} c_p\right)^2 h^{2(p+1-\nu)} \left(1 + O_P(h^2 + \frac{1}{\sqrt{nh}})\right)$$

$$+\frac{\sigma^2(x_0)}{f_X(x_0)nh^{2\nu+1}}e_{\nu+1}^T S_p^{-1}S_p^* S_p^{-1}e_{\nu+1}\left(1+O_P(h^2+\frac{1}{\sqrt{nh}})\right).$$

The result now follows directly from Lemma 1. □

Proof of Theorem 3. By Theorem 1 of Fan and Gijbels (1993),

$$E(\hat{\sigma}^2(x_0)|\underset{\sim}{X}) = \sigma^2(x_0) + O_P(h_*^{2(r+1)}),$$

and it can be shown that

$$\mathrm{Var}(\hat{\sigma}^2(x_0)|\underset{\sim}{X}) = O_P\left(\frac{1}{nh_*}\right).$$

Thus, using Assumption (vii), we obtain

$$\hat{\sigma}^2(x_0) = \sigma^2(x_0) + O_P\left(h_*^{2(r+1)} + \frac{1}{\sqrt{nh_*}}\right) = \sigma^2(x_0) + o_P((nh_*^{2p+3})^{-\frac{1}{2}}),$$

and hence

$$\left(\frac{\hat{\sigma}^2(x_0)}{\sigma^2(x_0)}\right)^{\frac{1}{2p+3}} = 1 + o_P\left((nh_*^{2p+3})^{-\frac{1}{2}}\right).$$

Now, by Theorem 1 of Fan, Heckman and Wand (1992),

$$\sqrt{\frac{nh_*^{2p+3}}{\gamma\sigma^2(x_0)/f_X(x_0)}}\left(\hat{\beta}_{p+1} - \beta_{p+1} - \alpha\beta_{r+1}h_*^{r-p}\right) \xrightarrow{D} N(0,1). \tag{4.10}$$

Note that equation (4.10) can also be proved directly by checking Lindeberg's condition. Evidently,

$$\left(\frac{\hat{\beta}_{p+1}}{\beta_{p+1}}\right)^{\frac{2}{2p+3}} = 1 + \frac{2(\hat{\beta}_{p+1} - \beta_{p+1})}{(2p+3)\beta_{p+1}} + O_P\left((\hat{\beta}_{p+1} - \beta_{p+1})^2\right).$$

Therefore,

$$\sqrt{\frac{nh_*^{2p+3}}{\gamma\sigma^2(x_0)/f_X(x_0)}}\left(\left(\frac{\hat{\beta}_{p+1}}{\beta_{p+1}}\right)^{\frac{2}{2p+3}} - 1 - \frac{2\alpha\beta_{r+1}}{(2p+3)\beta_{p+1}}h_*^{r-p}\right)$$
$$\xrightarrow{D} N\left(0, \left(\frac{2}{(2p+3)\beta_{p+1}}\right)^2\right).$$

Hence, it follows from Lemma 2 that

$$\sqrt{\frac{nh_*^{2p+3}}{\gamma\sigma^2(x_0)/f_X(x_0)}}\left(\frac{\hat{h}_\nu - h_{\nu,opt}}{h_{\nu,opt}} + \frac{2\alpha\beta_{r+1}}{(2p+3)\beta_{p+1}}h_*^{r-p}\right)$$
$$\xrightarrow{D} N\left(0, \left(\frac{2}{(2p+3)\beta_{p+1}}\right)^2\right),$$

which completes the proof. □

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Example 1: Typical estimated curves, n = 200

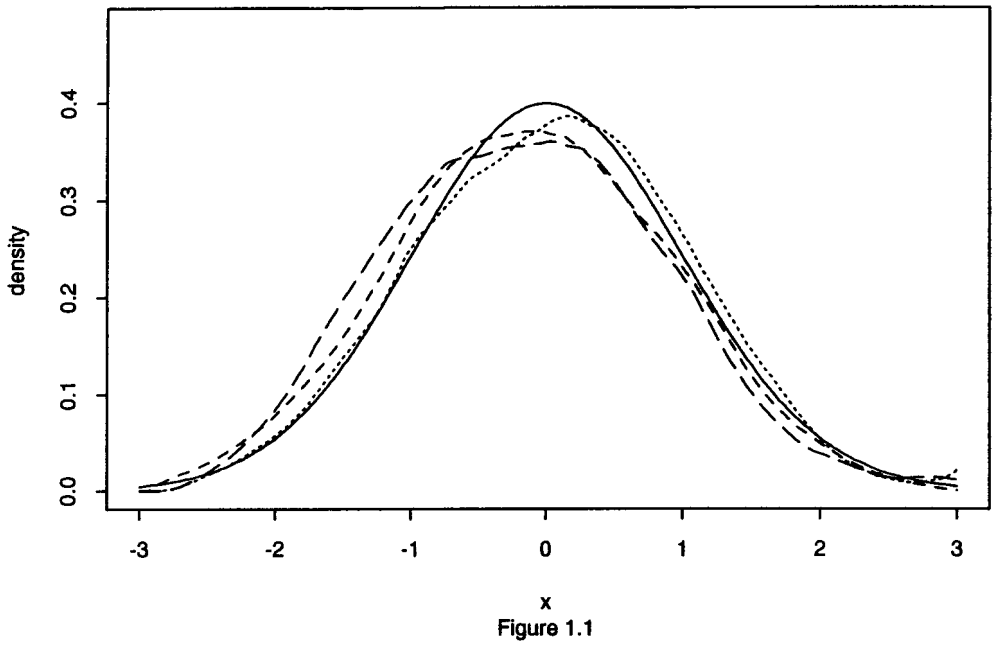

Figure 1.1

Example 2: Typical estimated curves, n = 200

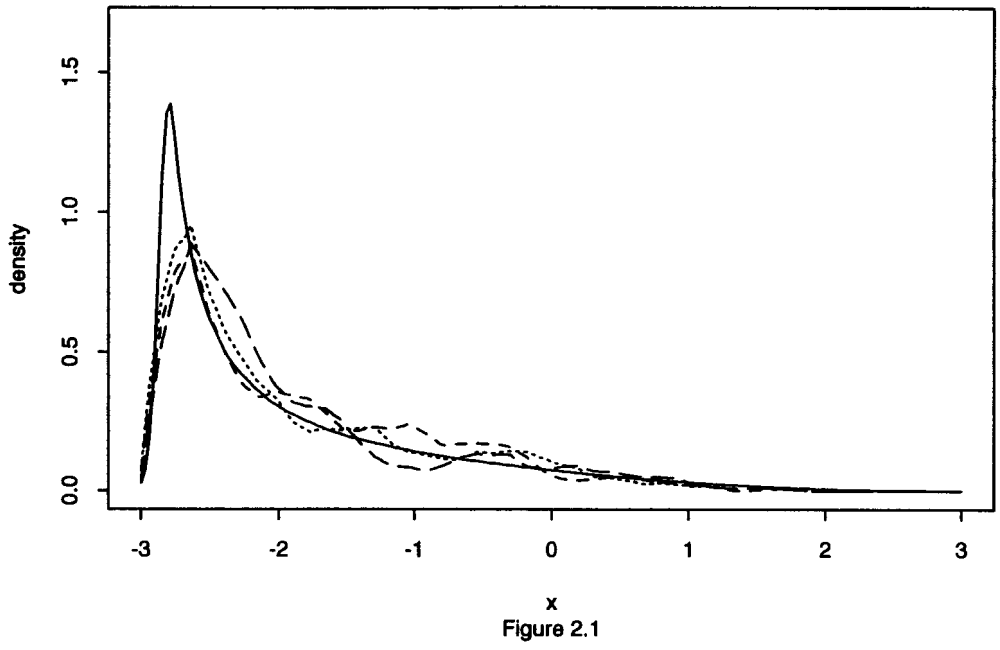

Figure 2.1

Example 3: Typical estimated curves, n = 200

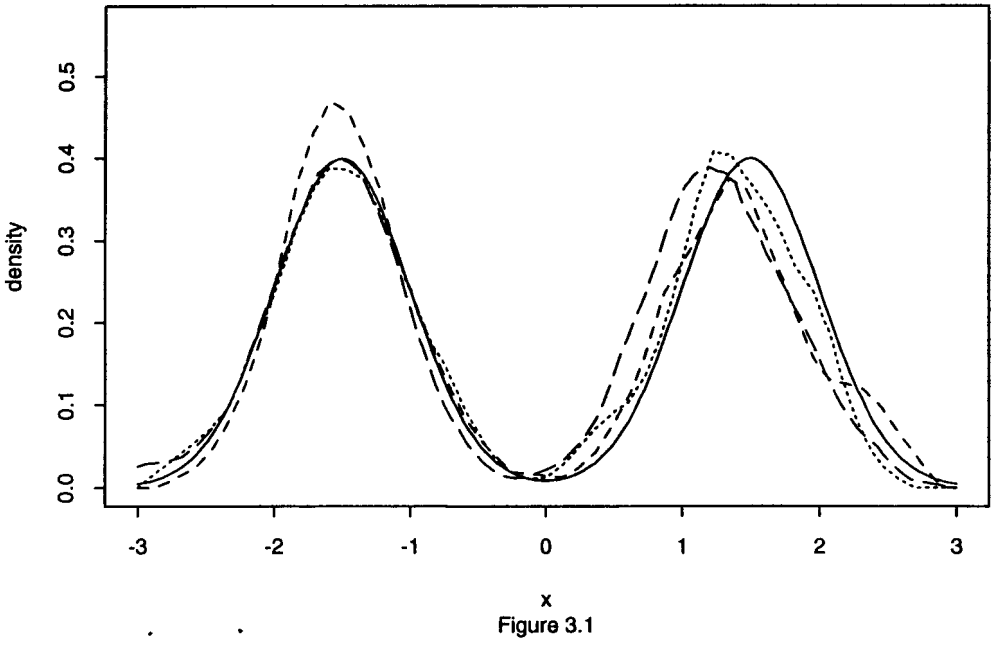

Figure 3.1

Example 4: Typical estimated curves, n = 200

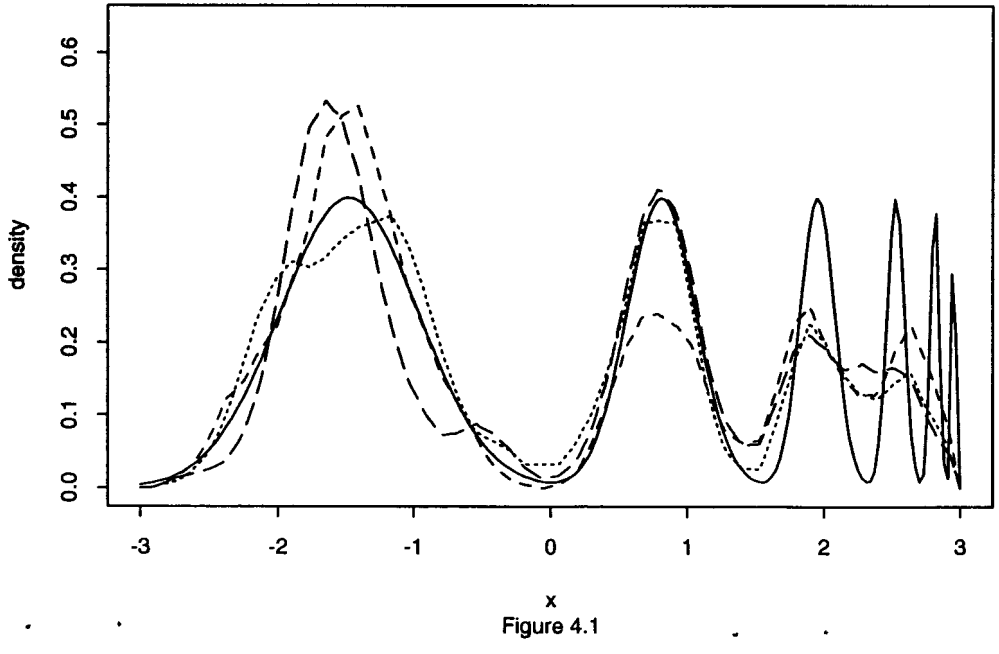

Figure 4.1

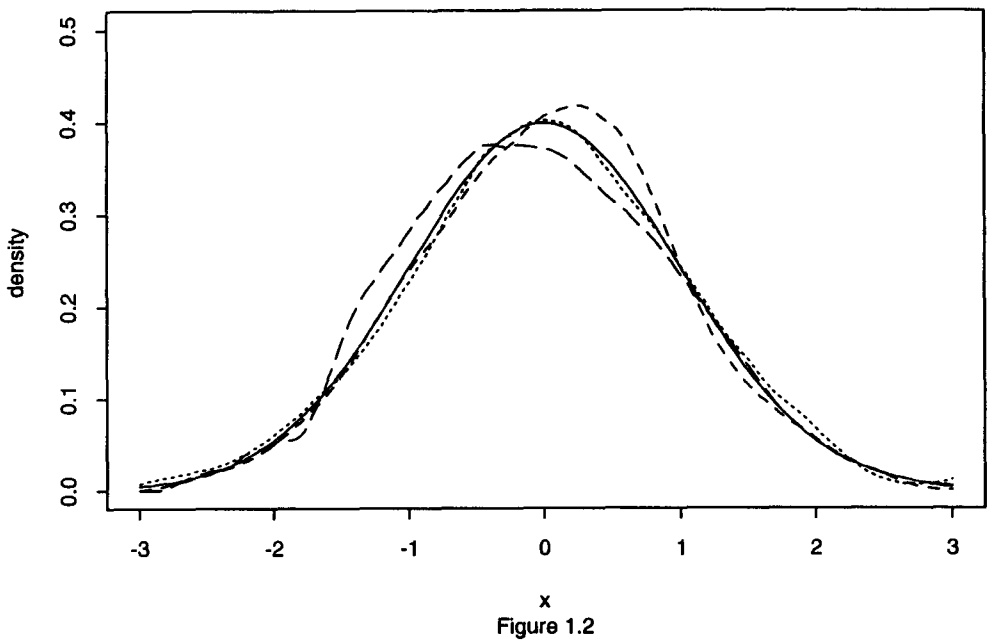

Figure 1.2

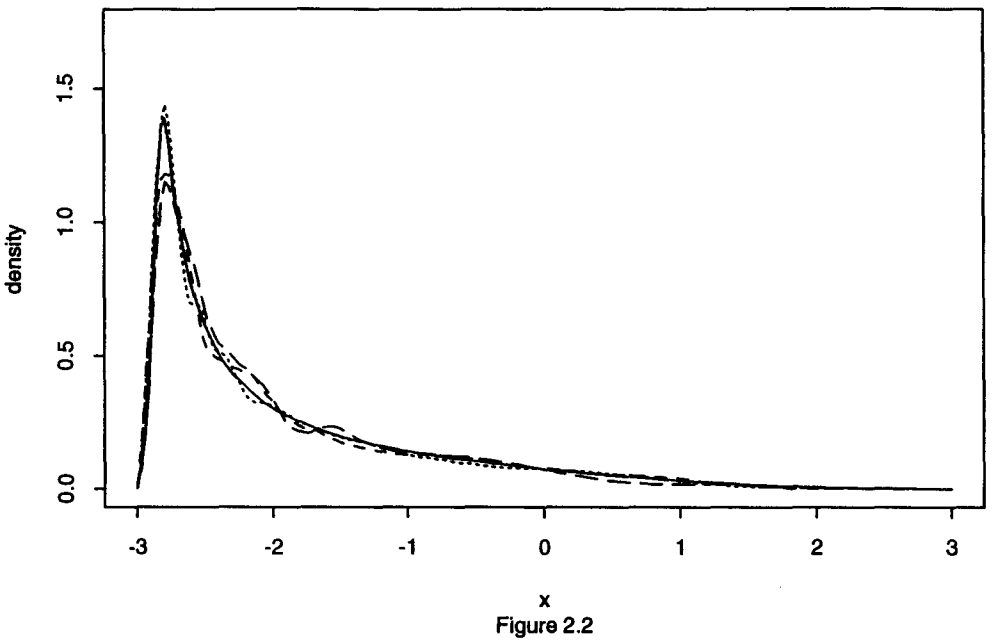

Figure 2.2

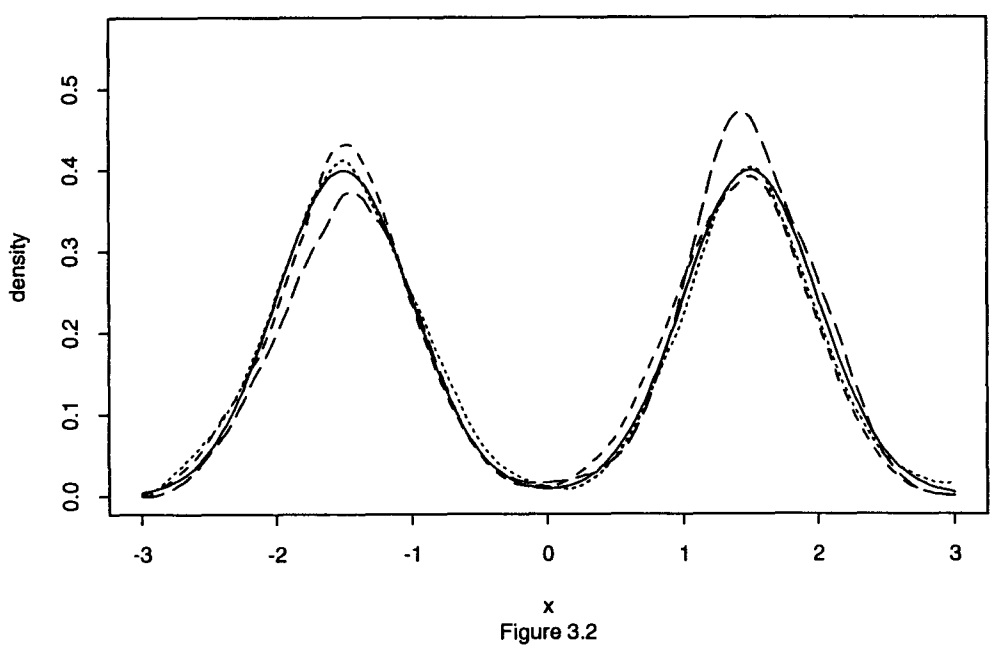

Figure 3.2

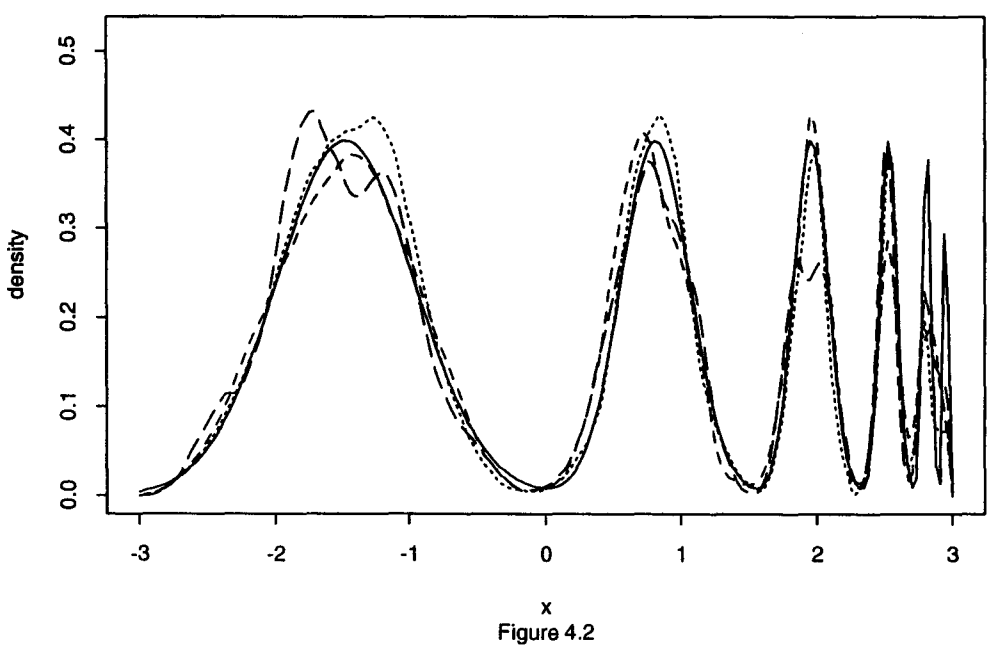

Figure 4.2